



CIRS: Bursting Filter Bubbles by Counterfactual Interactive Recommender System

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* Outline



1. Background and Motivation.

- Filter Bubbles in Recommendation
- Why Do we Choose the Interactive Recommendation?
- Empirical Study of User Satisfaction in Filter Bubbles
- Motivation of the idea
- 2. Related Works and Existing Problems
- 3. Proposed Method: CIRS
- 4. Experiments

1.1 Filter Bubbles in Recommendation

- □ Filter bubble
 - The phenomenon that recommender emphasizes only a small set of items in the feedback loop of the interaction process
 - □ Similar concepts: echo chamber, information cocoon



Filter bubbles in the recommendation-feedback loop

1.2 Why Interactive Recommender System (IRS)?

- Because IRS is the general form of real-world recommenders (static recommender is only a special/simplified case of IRS).
- Because IRS provides an environment to evaluate the effect of filter bubbles.



An interaction trajectory in Kuaishou, a video viewing App

1.2 Why Interactive Recommender System (IRS)?
 Because IRS is the general form of real-world recommenders (static recommender is only a special/simplified case of IRS).

Because IRS provides an environment to evaluate the effect of filter bubbles.
Formation of filter bubble

s: the **state** representing the context of the interaction.

r: the **reward** representing user satisfaction.

a: an **action**, e.g. a recommended item



The general framework of interactive recommendation

1.3 User Satisfaction in Filter Bubbles

Get bored

Assumption: Users may feel bored and give negative feedback in such a repeated and monotonous recommendation stream.



1.3 User Satisfaction in Filter Bubbles

Get bored

video stream in

Kuaishou App

Assumption: Users may feel bored and give negative feedback

in such a repeated and monotonous recommendation stream.

Empirical studies conducted on Kuaishou App.



Two important user behaviors reflecting satisfaction

Keeping watching until (1)quitting or scrolling to the

next one



Metric: Watching ratio

(watching time / video video time duration)

Hitting and staying in the (2)comments section



Metric: Time staying comments section

1.3 User Satisfaction in Filter Bubbles



Assumption: Users may feel bored and give negative feedback

in such a repeated and monotonous recommendation stream.



Observation 1: User satisfaction towards a recommended item drops when the system increases the number of similar items that have the same categories with this item in recent recommendations.
 Observation 2: User satisfaction towards a recommended item drops as the time interval between two similar items reduces.

1.4 Motivation of the idea

■ Propose an unbiased causal user model ϕ_M in the model-based offline reinforcement learning (RL) framework to disentangle the intrinsic user interest from the overexposure effect of items.



Save interaction data of policy π_{θ} : {(u, i, r, t)}

Traditional online interactive recommender

Counterfactual IRS (CIRS) based on offline RL learning * Outline



- **1. Background and Motivation.**
- 2. Related Works and Existing Problems
 - Efforts to Mitigate Filter Bubbles
 - Causal Inference-based Recommendation
 - Offline Learning for Online Recommenders
- 3. Proposed Method: CIRS
- 4. Experiments

2.1 Efforts to Mitigating Filter Bubbles

Existing Efforts



• Improve awareness of diverse social opinions (Gao et al. IUI' 18), (Donkers et al. RecSys' 21)

Improve the system's

- Diversity (Aridor et al, RecSys' 20) (Tommasel et al, RecSys' 21)
- Serendipity (Xu et al. TKDD' 20)
- Fairness (Masrour et al. AAAI' 20)

Study on

Whether the failed system can be cured by watching debunking content (Tomlein et al. RecSys' 21 Best Paper Award)

However, these efforts mainly focus on the solutions in the static setting, where the effect of filter bubbles is hard to observe and evaluate.

2.2 Causal Inference-based Recommendation

- Causal Inference (CI) has been widely used in NLP, CV, RS
- Instead of exploiting the correlation between input and output, CI explicitly models the causal mechanism among variables.
- General procedures (Judea Pearl, The Book of Why: The New Science of Cause and Effect)
 - 1. Construct a structure causal model (SCM) to describe the causal relationship among the related variables.
 - 2. Fit an unbiased model (e.g., implemented as a neural network) based on the SCM on the training data set.
 - 3. In the inference stage, we actively change certain input variables (called intervention) and predict the unbiased result of the target variable.

2.3 Offline Learning for Online Recommenders

- Static model is inflexible. Reinforcement learning (RL) introduces a policy that has the ability to adapt to the changing environment. However, it is impractical to train RL online. Because:
 - 1. for the model, the online interaction with humans is too slow.
 - 2. for users, interacting with a half-baked system can hurt experiences.

□ Solution: Offline Reinforcement Learning.



Sergey Levine et al. 2020, Offline Reinforcement Learning: Tutorial, Review, and Perspectives on Open Problems

2.3 Offline Learning for Online Recommenders

□ Solution: Offline Reinforcement Learning.

□ Off-Policy Evaluation via Importance Sampling:

- □ Main idea: Evaluate the target policy using historical policies.
- Problem: High variance

$$J(\pi_{\theta}) = \mathbb{E}_{\tau \sim \pi_{\beta}(\tau)} \left[\frac{\pi_{\theta}(\tau)}{\pi_{\beta}(\tau)} \sum_{t=0}^{H} \gamma^{t} r(\mathbf{s}, \mathbf{a}) \right]$$
$$= \mathbb{E}_{\tau \sim \pi_{\beta}(\tau)} \left[\left(\prod_{t=0}^{H} \frac{\pi_{\theta}(\mathbf{a}_{t} | \mathbf{s}_{t})}{\pi_{\beta}(\mathbf{a}_{t} | \mathbf{s}_{t})} \right) \sum_{t=0}^{H} \gamma^{t} r(\mathbf{s}, \mathbf{a}) \right] \approx \sum_{i=1}^{n} w_{H}^{i} \sum_{t=0}^{H} \gamma^{t} r_{t}^{i}, \tag{5}$$

where $w_t^i = \frac{1}{n} \prod_{t'=0}^t \frac{\pi_{\theta}(\mathbf{a}_{t'}^i | \mathbf{s}_{t'}^i)}{\pi_{\beta}(\mathbf{a}_{t'}^i | \mathbf{s}_{t'}^i)}$ and $\{(\mathbf{s}_0^i, \mathbf{a}_0^i, r_0^i, \mathbf{s}_1^i, \ldots)\}_{i=1}^n$ are *n* trajectory samples from $\pi_{\beta}(\tau)$ **Model-based Method:**

Main idea: estimate the environment, i.e., transition probability *T*(*s*_{t+1}|*s*_t, *a*_t)
 Problem: distribution shift, or **biases** in the estimated model.

Sergey Levine et al. 2020, Offline Reinforcement Learning: Tutorial, Review, and Perspectives on Open Problems

2.3 Offline Learning for Online Recommenders

□ Summarize RSs according to three dimensions

(1) whether the system explicitly builds a user model,

(2) whether the system considers debiasing, and

(3) whether the system has an **RL-based policy**.

	User Mode	l Debiasing	RL-based	Publications
Static RS	\checkmark			[14, 15, 21]
Unbiased static RS	\checkmark	\checkmark		[23, 24, 39, 41, 52, 61, 64, 66]
Traditional IRS			\checkmark	[25, 26, 28, 55, 60, 65, 67, 69]
Model-based IRS	\checkmark		\checkmark	[4, 8, 53, 62, 63, 68]
OPE-based IRS		\checkmark	\checkmark	[6, 18, 19, 30, 32, 47, 54]
Unbiased model- based IRS	\checkmark	\checkmark	\checkmark	[7, 16] CIRS (Ours)

Table 1: Six Types of Recommender Systems

* Outline



- **1. Background and Motivation.**
- 2. Related Works and Existing Problems

3. Proposed Method: CIRS

- Problem Definition
- Framework of CIRS
- Causal Inference-based User Satisfaction Disentanglement
- 4. Experiments

3.1 Problem Definition

Symbol Definition

 \square \mathcal{U},\mathcal{I} : the user set and the item set.

 $\square \mathcal{D}_u = \{\mathcal{S}_u^1, \mathcal{S}_u^2, \cdots, \mathcal{S}_u^{|\mathcal{D}_u|}\}: \text{ The set of all interaction sequence of a user } u \in \mathcal{U}.$

- $\begin{tabular}{ll} \hline $\mathcal{S}_{u}^{k} = \{(u,i_{l},t_{l})\}_{1 \leq l < |\mathcal{S}_{u}^{k}|}$ is the$ *k*-th interaction sequence (i.e., trajectory), where user*u* $begins to interact with the system at time <math>t_{1}$ and quits at time $t_{|\mathcal{S}_{u}^{k}|}$. i_{l} \in \mathcal{I}$ is the recommended item at time <math>t_{l}$. \end{tabular}$
- \square $\mathbf{e}_u \in \mathbb{R}^{d_u}$, $\mathbf{e}_i \in \mathbb{R}^{d_i}$: the representation vectors of user u and item i.

3.1 Problem Definition

Reinforcement learning problem:

- State: $s_t \in \mathbb{R}^{d_s}$ at time *t* is regarded as a vector representing information of all historical interactions of user *u*.
- Action: The system makes an action a_t at time is to recommend an item to the user. Let $\mathbf{e}_a \in \mathbb{R}^{d_a}$ be the representation vector. In this paper, $\mathbf{e}_a = \mathbf{e}_i$.
- Reward: A user u returns feedback as a reward score r reflecting its satisfaction after receiving a recommended item i.
- **Policy network:** $\pi_{\theta} = \pi_{\theta}(a_t|s_t)$ is the target policy that decides how to make an action a_t conditioned on the state s_t . In this paper, we use the Proximal Policy Optimization (PPO) algorithm as the policy network.

3.1 Problem Definition

The whole procedure



Save interaction data of policy π_{θ} : {(u, i, r, t)}

Counterfactual IRS (CIRS) based on offline RL learning

- 1. Train a user model ϕ_M via supervised learning on historical data $\{(u, i, r)\}$.
- 2. Using the learned user model ϕ_M to train policy π_{θ} . Each time the policy π_{θ} makes an action (i.e., a recommended item), the causal user model ϕ_M provides a *counterfactual reward* r. If π_{θ} have made similar recommendations before, ϕ_M shrinks the reward r.
- 3. Serving the learned policy π_{θ} to users and evaluating the results in the real environment.



Three modules in CIRS

DCausal User Model ϕ_M

- Preference estimation
- Causal intervention

DRL Policy π_{θ}

Interactive strategy

□ State Tracker

Recording interaction context



Transformer-based State Tracker

The states are derive from:

User representation:

 $\mathbf{e}'_u = FFN(\mathbf{e}_u)$

Action representation obtained from a gate mechanism:

 $\mathbf{e}_{a_t}' = \boldsymbol{g}_t \odot \mathbf{e}_{a_t},$

where $\boldsymbol{g}_t = \sigma (\boldsymbol{W} \cdot Concat(\boldsymbol{r}_t, \boldsymbol{e}_{a_t}) + \boldsymbol{b})$



RL-based Interactive Recommendation Policy

 $\square \pi_{\theta}$: **PPO algorithm**, an on-policy policy gradient method in RL.

□ Maximize the objective:

$$\mathbb{E}_{t}\left[\min\left(\frac{\pi_{\theta}(a_{t}|s_{t})}{\pi_{\theta_{old}}(a_{t}|s_{t})}\hat{A}_{t}, clip\left(\frac{\pi_{\theta}(a_{t}|s_{t})}{\pi_{\theta_{old}}(a_{t}|s_{t})}, 1-\epsilon, 1+\epsilon\right)\hat{A}_{t}\right)\right]$$

 $\pi_{\theta_{old}}$: the policy generating the data

 π_{θ} : the updating policy

 \hat{A}_t : the advantage function

Schulman et al. Proximal Policy Optimization Algorithms. arXiv:1707.06347 (2017)



Causal User Model

- 1. Estimate user preference using a naive recommendation model, e.g., *DeepFM*.
- 2. Disentangle the intrinsic user interest from the overexposure effect of items.

Structure Causal Model



- U: a certain user u, e.g., an ID or the profile feature that can represent the user.
- *I*: an item *i* that is recommended to user *u*.
- *R*: the **user satisfaction**, also used as the *reward*.
- *Y*: **intrinsic user interest** (regardless of item exposure)
- E_t : the **overexposure effect** of item *i* on user *u*. Where e_t^* is the value of E_t computed in the inference stage (RL planning stage).

Structure Causal Model



Two paths in (b):

 $(U, I) \rightarrow Y \rightarrow R$: projects user and item features into the corresponding preference $\hat{y}_{ui} = f_{\theta}(u, i)$, which can be implemented by various recommendation models (DeepFM).

 $I \rightarrow E_t \rightarrow R$: represents the real-time overexposure effect e_t^* of an item *i* on user *u* that eventually results in the user satisfaction *r*.

Definition of overexposure effect E_t

$$e_t = e_t(u, i) = \alpha_u \beta_i \sum_{\{(u, i_l, t_l) \in S_u^k, t_l < t\}} \exp\left(-\frac{t - t_l}{\tau} \times dist(i, i_l)\right)$$

- $S_u^k = \{(u, i_l, t_l)\}_{1 \le l < |S_u^k|}$ is the *k*-th interaction sequence (i.e., trajectory) of user *u*.
- $dist(i, i_l)$: is distance between two items *i* and i_l .
- α_u : represents the *sensitivity* of user *u* to the overexposure effect
- β_i : represents the *unendurableness* of item *i*.

Definition of user satisfaction \hat{r}_{ui}^t

$$\hat{r}_{ui}^t = \frac{\hat{y}_{ui}}{1 + e_t(u, i)}$$

Loss function in training user model:

$$L_{BPR} = -\sum_{\{(u,i,t)\in D, j\sim p_n\}} \log(\sigma(\hat{r}_{ui}^t - \hat{r}_{uj}^t))$$

Definition of overexposure effect E_t

$$e_t = e_t(u, i) = \alpha_u \beta_i \sum_{\{(u, i_l, t_l) \in S_u^k, t_l < t\}} \exp\left(-\frac{t - t_l}{\tau} \times dist(i, i_l)\right) \qquad (U)$$



Causal Intervention on Overexposure Effect

$$\boldsymbol{e}_{t}^{*} = \boldsymbol{\gamma}^{*} \cdot \boldsymbol{\alpha}_{u} \boldsymbol{\beta}_{i} \sum_{\{(u, \boldsymbol{i}_{l}^{*}, \boldsymbol{t}_{l}^{*}) \in \boldsymbol{S}_{u}^{*}, \boldsymbol{t}_{l}^{*} < t\}} \exp\left(-\frac{t - \boldsymbol{t}_{l}^{*}}{\tau^{*}} \times dist(\boldsymbol{i}, \boldsymbol{i}_{l}^{*})\right) \boldsymbol{U}^{*}$$

Variables with Asterisk " * " are these in the inference stage (i.e., RL planning stage)

Adjusted user satisfaction \hat{r}_{ui}^{t*}

$$\hat{r}_{ui}^{t*} = \frac{\hat{y}_{ui}}{1 + e_t^*(u, i)}$$



 e_t^*

* Outline



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4. Experiments

- Experimental Setup
- Performance Comparison
- More Analysis

Recommendation Environments: 1. VirtualTaobao

- A benchmark RL environment for recommendation.
- Created by simulating the behaviors of real users on Taobao.
- A user is represented as an 88-dimensional vector $\mathbf{e}_u \in \{0,1\}^{88}$
- An item is represented as a 27-dimensional vector $\mathbf{e}_i \in \mathbb{R}^{27}$, $0 \le \mathbf{e}_i \le 1$.
- When a recommender makes an action, the environment will immediately return a *reward* representing the number of clicks, *r* ∈ {0,1,…,10}.

Recommendation Environments: 2. KuaiEnv

	#users	#Items	#Interactions	Density
Small matrix	1,411	3,327	4,676,570	99.6%
Big matrix	7,176	10,729	12,530,806	13.4%

Item feature:	Each video has at least 1 and at most 4 tags out of the totally 31 tags, e.g., {Sports}.
Social network:	Small matrix: 146 users have friends. Big matrix: 472 users have friends.

User-item matrix



(a) Traditional recommendation datasets



Unobserved value



Small matrix: The fully observed data used for evaluating the model.

Big matrix: Additional interactions used for training the model.

(b) The User-item matrices in the proposed *KuaiRec*

Exit Mechanism:



Compute distance (VirtualTaobao: Euclidean distance,

KuaishouEnv: Check if there is a overlapped attribute)

Feature vectors of items

- VirtualTaobao: 27-dim continuous vectors
- KuaishouEnv: 31-dim multi-hot vectors

Exit mechanism:

- VirtualTaobao: Quit if any distance lower than d_o .
- KuaishouEnv: Quit if more than n_0 items have overlapped attributes.

Evaluation metric:

Accumulated reward = $\sum_{t=1}^{T} r_t$, which requires:



Baselines (*Recommendation Model + Policy*)

- **DeepFM** (*DeepFM* + *Softmax Sampling*)
- **IPS** (*IPS* + *Softmax Sampling*)
- **PD** (*PD* + Softmax Sampling)
- **DICE** (*DICE* + *Softmax Sampling*)
- **MLP** (*MLP* + SoftMax Sampling)
- Random
- ϵ -greedy (DeepFM + ϵ -greedy)
- UCB (DeepFM + UCB)
- **CIRS** (User Model + PPO)
- CIRS w/o CI (CIRS without causal inference module)





Insights:

IPS

1. CIRS achieves maximal accumulated reward.

→ MLP → PD → Random → UCB

- 2. Interestingly, in A2, increasing of the reward in each round compromises the length of trajectory in the beginning. But finds a balance in the end.
- 3. CIRS w/o CI is unstable and the performance degenerates with epoch increasing.
- 4. Random in VirtualTaobao cannot bring longer length because of curse of dimensionality.
- 5. IPS has high variance.
- 6. UCB shows the effect of E&E, but it cannot address filter bubble problem.

Insights:

In VirtualTaobao, both policies achieve the same level of singleround performance as the static methods.

In KuaishouEnv, Armed with causal inference, CIRS beats its counterpart greatly.



Results under different user sensitivity



- When users become more sensitive, the performance of CIRS and CIRS w/o CI drop.
- Other baselines are not suitable in addressing filter bubbles.

4.3 Analysis Effect of Key Parameters



- An active user is easier to get bored when viewing overexposed videos.
- Popular videos are less endurable when they are overexposed.

4.3 Analysis Effect of Key Parameters



Insights:

- Suitable (τ, τ^*) pair indeed improve the performance.
- The orders of magnitude of τ and τ* are different because the unit of time is different, i.e., second(s) vs. step(s).



- The first work for learning to burst filter bubbles in interactive recommendation, where filter bubbles can be observed and evaluated.
- Proposed the CIRS based on offline reinforcement learning. We are the first to utilize the causal inference in interactive recommendation.
- 3. Collected a **fully filled dataset** (density: 100\%) from Kuaishou to create an interactive recommendation environment.
- 4. The **experiments** show that our proposed model can burst filter bubbles and gain the maximal accumulative rewards.





Thanks

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